

Semiparametric and Nonparametric Methods in Political Science

Lecture 1: Semiparametric Estimation

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Overview of Semi and Nonparametric Models

- Parametric Model: statistical model characterized by finite dimensional unknown parameter
 - $y_n \sim N(\mu, \sigma^2)$
 - $y_n \sim N(\beta' x_n, \sigma^2)$ (normal-linear model)
- Nonparametric Model: statistical model characterized by infinite dimensional unknown parameter
 - $y_n \sim f$ where f is unknown (density estimation)
 - $y_n = g(x_n) + \varepsilon_n$, $E[\varepsilon_n | x_n] = 0$ (nonparametric regression)

Overview of Semi and Nonparametric Models

- Semiparametric Model: statistical model characterized by finite dimensional parameter of interest and infinite dimensional “nuisance” parameter
 - $y_n = \beta' x_n + \varepsilon_n$, $\varepsilon_n | x_n \sim F(\varepsilon | x)$ with $E[\varepsilon_n | x_n] = 0$ (semiparametric linear model)
 - β is “parameter of interest”
 - F is a nuisance parameter
 - $y_t = \beta' x_t + \varepsilon_t$, (x_t, ε_t) is stationary and ergodic and $E[\varepsilon_t | x_t] = 0$
 - β is “parameter of interest”
 - Stochastic process characterizing (x_t, ε_t) is a nuisance parameter

Overview of Semi and Nonparametric Models

- More Semiparametric/Nonparametric Models:

- $y_n = g(\beta'x_n) + \varepsilon_n$, $\varepsilon_n | x_n \sim F(\varepsilon | x)$ with $E[\varepsilon_n | x_n] = 0$ (linear index model)
- $y_n = g(x_n) + \beta'z_n + \varepsilon_n$, $\varepsilon_n | x_n \sim F(\varepsilon | x)$ with $E[\varepsilon_n | x_n] = 0$ (partially linear model)
- $\Pr(y_n = 1) = G(\beta'x_n)$ (semiparametric binary choice)

Overview of Semi and Nonparametric Models

- Parametric Models:

- MLE is efficient if parametric model is correct
- MLE is often inconsistent if parametric model is incorrect
- \sqrt{N} -convergence rate

- Nonparametric Models:

- More generality, but...
 - Theory more difficult
 - Implementation difficult
 - Slower convergence (slower than parametric rate of \sqrt{N})
 - Efficiency loss (relative to MLE if parametric model is corr.)

Overview of Semi and Nonparametric Models

- Semiparametric Models:
 - More generality, and...
 - Often, \sqrt{N} -convergence for parameter of interest
 - Often, easy to implement
 - Often, little efficiency loss
 - Theory can be very hard, but some important cases are sufficiently worked out so that we don't have to worry about it
- Lecture 1 will focus on easy but powerful semiparametric estimators
- Lecture 2 will focus on basics of nonparametric estimation
- Lecture 3 will focus on applications of nonparametric estimators and more advanced semiparametric estimators

Overview of Semi and Nonparametric Models

- Examples of “Easy” Semiparametric Estimators:
 - OLS w/ robust se's - semiparametric because OLS is consistent even if error terms are non-normal and heteroskedastic
 - Poisson regression w/ robust se's - semiparametric because estimator is consistent when dependent variable is not Poisson distributed
 - Linear-nonlinear models w/ Newey-West se's – semiparametric because OLS/MLE are consistent even when dependent variable exhibits time series dependence
 - Short panels with clustered standard errors – semiparametric because OLS/MLE are consistent even when dependent variable exhibits group correlation/time series dependence

Overview of Semi and Nonparametric Models

- Why Use These Semiparametric Estimators?
 - Easy to apply:
 - Some parametric alternatives are VERY computationally intensive
 - Skip the specification step (which is sometimes near impossible)
 - Modeling heteroskedasticity
 - Selecting ARMA structure (w/ time series and panel data)
 - Selecting between negative binomial, zero-inflated, zero-truncated, etc., in count models

Overview of Semi and Nonparametric Models

- Drawbacks:
 - Efficiency loss relative to parametric model
- However:
 - Parametric model may be wrong!
 - Usually, semiparametric estimators achieve semiparametric efficiency bounds (they are efficient under maintained assumptions)
 - Often, not much efficiency loss
 - Often, these semiparametric estimators give robustness practically “for free” since we don’t have to estimate the nuisance parameters

Heteroskedasticity in the Linear Model

- **Parametric** Linear Model:

1. $y_n = \beta_0' x_n + \varepsilon_n$ (linearity)

2. (x_n, ε_n) are independent (independence)

3. $E[x_n x_n']$ has full rank (identification)

4. $E[\varepsilon_n | x_n] = 0$

5. $\varepsilon_n \sim N(0, \sigma^2)$ (homoskedasticity and normality)

- Under 1-5, OLS is MLE; OLS is unbiased, normally distributed, consistent, and asymptotically normal; the information equality holds; and OLS is efficient

Heteroskedasticity in the Linear Model

- **Semiparametric** Linear Model:

1. $y_n = \beta_0' x_n + \varepsilon_n$ (linearity)

2. (x_n, ε_n) are independent (independence)

3. $E[x_n x_n']$ has full rank (identification)

4. $E[\varepsilon_n | x_n] = 0$

- ~~5. $\varepsilon_n \sim N(0, \sigma^2)$ (homoskedasticity and normality)~~

- Consider OLS as semiparametric estimator

- Under 1-4, OLS is unbiased, ~~normally distributed~~, consistent, and asymptotically normal; ~~the information equality holds~~; and ~~OLS is efficient~~

Heteroskedasticity in the Linear Model

- Properties of OLS as semiparametric estimator:

$$\hat{\beta} = \left[\frac{1}{N} \sum_{n=1}^N x_n x_n' \right]^{-1} \left[\frac{1}{N} \sum_{n=1}^N x_n y_n \right] = \beta_0 + \left[\frac{1}{N} \sum_{n=1}^N x_n x_n' \right]^{-1} \left[\frac{1}{N} \sum_{n=1}^N x_n \varepsilon_n \right]$$

$y_n = (\beta_0' x_n + \varepsilon_n)$

- By law of iterated expectations,

$$E[x_n \varepsilon_n] = E[x_n E[\varepsilon_n | x_n]] = 0$$

$=0$

- OLS is unbiased:

$$E[\hat{\beta} | x] = \beta_0 + \left[\frac{1}{N} \sum_{n=1}^N x_n x_n' \right]^{-1} \left[\frac{1}{N} \sum_{n=1}^N E[x_n \varepsilon_n] \right] = \beta_0$$

$=0$

Heteroskedasticity in the Linear Model

- OLS is consistent:

$$\frac{1}{N} \sum_{n=1}^N x_n \varepsilon_n \xrightarrow{\text{prob.}} E[x_n \varepsilon_n] = 0$$

=0

$$\hat{\beta} = \beta_0 + \left[\frac{1}{N} \sum_{n=1}^N x_n x_n' \right]^{-1} \left[\frac{1}{N} \sum_{n=1}^N x_n \varepsilon_n \right] \xrightarrow{\text{prob.}} \beta_0 + \left[\frac{1}{N} \sum_{n=1}^N x_n x_n' \right]^{-1} 0 = \beta_0$$

prob. → 0

- Normality/homoskedasticity not needed for these results

Heteroskedasticity in the Linear Model

- OLS is asymptotically normal:

$$\sqrt{N}(\hat{\beta} - \beta_0) = \begin{bmatrix} \frac{1}{N} \sum_{n=1}^N x_n x_n' \end{bmatrix}^{-1} \begin{bmatrix} \frac{1}{\sqrt{N}} \sum_{n=1}^N x_n \varepsilon_n \end{bmatrix}$$

$$\downarrow \text{LLN} \qquad \qquad \downarrow \text{CLT}$$

$$E[x_n x_n']^{-1} \qquad N(0, \text{Var}(x_n \varepsilon_n))$$

$$\sqrt{N}(\hat{\beta} - \beta_0) \xrightarrow{\text{dist.}} N(0, \underbrace{E[x_n x_n']^{-1}}_{\text{bread}} \underbrace{\text{Var}(x_n \varepsilon_n)}_{\text{meat}} \underbrace{E[x_n x_n']^{-1}}_{\text{bread}})$$

- Estimate asymptotic distribution using:

$$E[x_n x_n']^{-1} \approx \frac{1}{N} \sum_{n=1}^N x_n x_n'$$

$$\text{Var}(x_n \varepsilon_n) = E[\varepsilon_n^2 x_n x_n'] \approx \frac{1}{N} \sum_{n=1}^N \varepsilon_n^2 x_n x_n'$$

Heteroskedasticity in the Linear Model

- Implementation:
 - In stata, “regress y x1 x2, robust”
 - In r, use *sandwich* package:
 - “lm1 <- lm(Y ~ X1 + X2)”
 - “sw1 <- sandwich(lm1)”

Heteroskedasticity in the Linear Model

- Overview:
 - Apply OLS when homoskedasticity/normality do not hold
 - Benefit: robustness
 - Drawback: less efficiency

Heteroskedasticity in the Linear Model

- Example:
 - OLS is MLE when errors are normal and homoskedastic
 - LAD is MLE when errors are double exponential and homoskedastic
 - OLS will be more efficient than LAD when errors are normal and homoskedastic, robust se's will be correct for both estimators
 - LAD will be more efficient than OLS when errors are double exponential and homoskedastic, robust se's will be correct for both estimators

Heteroskedasticity in the Linear Model

- Example Continued:

- Generate 1000 Monte Carlo data sets with $N=500$, $X1 \sim N(0,1)$, $X2 \sim N(0,1)$, $Beta = (-.5, 1.5, -1.0)$, and errors either $N(0,1)$ or $DExp(0,1)$

	DGP = Normal-Linear			DGP = DExp-Linear		
	<i>Beta1</i>	<i>Beta2</i>	<i>Beta3</i>	<i>Beta1</i>	<i>Beta2</i>	<i>Beta3</i>
Rel. Eff. OLS/LAD	0.81	0.80	0.82	1.31	1.37	1.28
OLS Overconfidence	1.06	1.04	1.05	0.97	1.02	1.02
LAD Overconfidence	1.04	1.04	1.02	0.98	0.98	1.04
OLS se / LAD se	0.89	0.89	0.89	1.15	1.15	1.15

Nonproportional Dispersion in Count Models

- Parametric Poisson Model:

1. $y_n \sim \text{Poisson}(\lambda_n)$, $\lambda_n = e^{\beta_0' x_n}$

2. (y_n, x_n) are iid

- Notice that $E[y_n | x_n] = \text{Var}(y_n | x_n) = \lambda_n = e^{\beta_0' x_n}$
- We can derive the log-likelihood function:

$$l(y, x; \beta) = \sum_{n=1}^N y_n \beta' x_n - e^{\beta' x_n} - \log y_n !$$

Nonproportional Dispersion in Count Models

- Semiparametric Poisson Model:

1. ~~$y_n \sim \text{Poisson}(\lambda_n), \lambda_n = e^{\beta_0' x_n}$~~ $E[y_n | x_n] = e^{\beta_0' x_n}$

2. (y_n, x_n) are iid

- Semiparametric estimator defined by:

$$\hat{\beta} = \arg \max_{\beta} \frac{1}{N} \sum_{n=1}^N y_n \beta' x_n - e^{\beta' x_n} - \log y_n !$$

Nonproportional Dispersion in Count Models

- Consistency of semiparametric Poisson regression:

$$\hat{\beta} = \arg \max_{\beta} \frac{1}{N} \sum_{n=1}^N y_n \beta' x_n - e^{\beta' x_n} - \log y_n !$$

- First order condition:

$$0 = \frac{1}{N} \sum_{n=1}^N x_{n,k} (y_n - e^{\hat{\beta}' x_n})$$

- In large samples:

$$0 = E[x_{n,k} (y_n - e^{\hat{\beta}' x_n})] = E[x_{n,k} E[(y_n - e^{\hat{\beta}' x_n}) | x_n]] = E[x_{n,k} (e^{\beta_0' x_n} - e^{\hat{\beta}' x_n}) | x_n]]$$

- Hence, $\hat{\beta} \xrightarrow{prob.} \beta_0$ as long as conditional mean is correctly specified (even if Poisson assumption does not hold)

Nonproportional Dispersion in Count Models

- What about standard errors?
- Define $\psi(y_n, x_n; \beta) = y_n \beta' x_n - e^{\beta' x_n} - \log y_n !$
- Taylor expansion argument:

$$\sqrt{N}(\hat{\beta} - \beta_0) \xrightarrow{dist.} N(0, Q^{-1} V Q^{-1})$$

where,

$$Q = E[\psi_{\beta\beta}(y_n, x_n; \beta_0)], \quad V = \text{Var}(\psi_{\beta}(y_n, x_n; \beta_0))$$

- If MLE assumptions hold, $Q = -V$
- If not, must use “sandwich” estimator, i.e. robust se’s

Nonproportional Dispersion in Count Models

- Implementation:
 - In stata: “poisson y x1 x2, robust”
 - In r, use *sandwich* package:
 - “pm1 <- glm(Y ~ X1 + X2,family=”poisson”)”
 - “sw1 <- sandwich(pm1)”

Nonproportional Dispersion in Count Models

- What we get:
 - Robustness to overdispersion
 - Robustness to zero-inflation, zero-truncation, one inflation, etc.
 - All we need is correctly specified conditional mean
- What we don't get
 - Efficiency (MLE is more efficient if parametric model is correct)
 - Predicted values easily generated, but not predicted distribution (since distribution is not Poisson)
 - If we want predicted values, we can use procedures discussed in lecture 3

Nonproportional Dispersion in Count Models

- Same principal extends to negative binomial model
- Same principal extends to other exponential family models (i.e. consistency holds as long as conditional mean is correctly specified)
- “, robust” does not provide any benefit for logit, probit, ordered logit, multinomial logit, etc.:
 - These models are only correct if parametric model is correct
 - If parametric model is correct, se's = robust se's in large samples

Time Series Dependence in the Linear Model

- Semiparametric Time Series Linear Model:
 1. $y_t = \beta_0' x_t + \varepsilon_t$ (linearity)
 2. ~~(x_t, ε_t) are independent~~ (x_t, ε_t) are stationary and ergodic
 3. $E[x_t x_t']$ has full rank (identification)
 4. $E[\varepsilon_t | x_t] = 0$
 5. ~~$\varepsilon_t \sim N(0, \sigma^2)$ (homoskedasticity and normality)~~
- Consider OLS as semiparametric estimator
- Under 1-4, OLS is unbiased, ~~normally distributed~~, consistent, and asymptotically normal; ~~the information equality holds; OLS is efficient~~

Time Series Dependence in the Linear Model

- OLS estimator: $\hat{\beta} = \beta_0 + \left[\frac{1}{T} \sum_{t=1}^T x_t x_t' \right]^{-1} \left[\frac{1}{T} \sum_{t=1}^T x_t \varepsilon_t \right]$
- OLS is unbiased: $E[\hat{\beta} | x] = \beta_0 + \left[\frac{1}{T} \sum_{t=1}^T x_t x_t' \right]^{-1} \left[\frac{1}{T} \sum_{t=1}^T E[x_t \varepsilon_t] \right] = 0$
=0
- Under stationarity and ergodicity, $\frac{1}{T} \sum_{t=1}^T x_t \varepsilon_t \xrightarrow{prob.} E[x_t \varepsilon_t] = 0$
- Hence, OLS is consistent

Time Series Dependence in the Linear Model

- Large sample distribution:

$$\sqrt{T}(\hat{\beta} - \beta_0) = \left[\frac{1}{T} \sum_{t=1}^T x_t x_t' \right]^{-1} \left[\frac{1}{\sqrt{T}} \sum_{t=1}^T x_t \varepsilon_t \right]$$

\downarrow *LLN* \downarrow *CLT*

$$E[x_t x_t']^{-1} \quad N\left(0, \lim_{T \rightarrow \infty} \text{Var}\left(\frac{1}{\sqrt{T}} \sum_{t=1}^T x_t \varepsilon_t\right)\right)$$

=Q =V

$$\sqrt{T}(\hat{\beta} - \beta_0) \xrightarrow{\text{dist.}} N(Q^{-1}VQ^{-1})$$

Time Series Dependence in the Linear Model

- Tricky part is estimating $V = \lim_{T \rightarrow \infty} \text{Var} \left(\frac{1}{\sqrt{T}} \sum_{t=1}^T x_t \varepsilon_t \right)$

- If $x_t \varepsilon_t$ are independent, then

$$\text{Var} \left(\frac{1}{\sqrt{T}} \sum_{t=1}^T x_t \varepsilon_t \right) = \frac{1}{T} \sum_{t=1}^T E[\varepsilon_t^2 x_t x_t'] \approx \frac{1}{T} \sum_{t=1}^T \varepsilon_t^2 x_t x_t'$$

- If $x_t \varepsilon_t$ not independent, then covariance terms make it hard

$$\text{Var} \left(\frac{1}{\sqrt{T}} \sum_{t=1}^T x_t \varepsilon_t \right) = \frac{1}{T} \sum_{t=1}^T \text{Var}(x_t \varepsilon_t) + \frac{2}{T} \sum_{s < t} \text{Cov}(x_t \varepsilon_t, x_s \varepsilon_s)$$

- Newey-West (and related procedures) provide a way to estimate

$$\lim_{T \rightarrow \infty} \text{Var} \left(\frac{1}{\sqrt{T}} \sum_{t=1}^T x_t \varepsilon_t \right)$$

Time Series Dependence in the Linear Model

- Define,

$$\hat{\gamma}(s) = \frac{1}{T-s-1} \sum_{t=s+1}^T \varepsilon_t \varepsilon_{t-s} x_t x_{t-s}'$$

and estimate,

$$\hat{V} = \hat{\gamma}(0) + \sum_{s=1}^{m_T} \left(1 - \frac{s}{m_T+1}\right) [\hat{\gamma}(s) + \hat{\gamma}(s)']$$

- Select m_T such that $m_T \rightarrow \infty$ as $T \rightarrow \infty$
- Automatic procedures for choosing m_T efficiently are available
- Rule of thumb is $m_T = \left\lfloor 4 \left(\frac{T}{100} \right)^{2/9} \right\rfloor$
- Newey-West is special case of spectral density approach to covariance matrix estimation (w/ a Bartlett Kernel)

Time Series Dependence in the Linear Model

- What we get:
 - Robustness to heteroskedasticity and autocorrelation
 - No need to select appropriate ARMA model (there is some bandwidth selection going on in the background, but this part is largely automated)
- What we lose:
 - Efficiency: If correct ARMA model is selected, then MLE will be more efficient

Time Series Dependence in Nonlinear Models

- Newey-West standard errors can be used to correct for time series dependence in nearly any nonlinear model
- For many nonlinear models, incorporating time series dependence is extremely difficult
- Parametric time-series versions of standard estimators cannot be estimated in most (or even all?) statistical packages
 - Time series logit, time series probit, time series count, etc.

Time Series Dependence in Nonlinear Models

- Binomial Probit with AR1 errors (parametric model)
 1. $y_t^* = \beta' x_t + \varepsilon_t$, $y_t = 1\{y_t^* \geq 0\}$ (probit model)
 2. $\varepsilon_t = \rho \varepsilon_{t-1} + u_t$, $u_t \sim N(0,1)$, u_t are iid (AR1 errors)
- MLE involves complicated T -dimensional integral
 - Define $A(y_1, \dots, y_T) = \{x : x_t \in [0, \infty) \text{ if } y_t = 1, x_t \in (-\infty, 0] \text{ if } y_t = 0\}$
 - $\mu_t(x; \beta) = \beta' x_t$, $\Omega_{s,t}(\rho) = \frac{\rho^{|s-t|}}{1-\rho}$
 - $\Pr(y_1, \dots, y_T; \beta, \rho) = \int_{\mathcal{G} \in A(y_1, \dots, y_T)} \phi(\mathcal{G}; \mu(x; \beta), \Omega(\rho)) d\mathcal{G}$
- Really hard to compute! (stata/r don't do it right now)

Time Series Dependence in Nonlinear Models

- Alternative approach: semiparametric estimation
- Claim (Poirier and Ruud, 1986): Probit is still consistent when observations are dependent

- Why?

- MLE is $\hat{\theta} = \arg \max_{\theta} \frac{1}{T} \sum_{t=1}^T \log f(y_t; \theta)$
- MSE is consistent because $\frac{1}{T} \sum_{t=1}^T \log f(y_t; \theta) \rightarrow E[\log f(y_t; \theta)]$
- Information inequality implies $E[\log f(y_t; \theta)]$ is minimized at θ_0 , the “true” parameter value
- Information inequality will continue to hold for all models that have the same marginals

Time Series Dependence in Nonlinear Models

- Hence, we can apply Newey-West standard errors to probit to obtain consistent estimates with correct standard errors
- Same result holds for other models:
 - Parametric Poisson models w/ time series dependence are difficult to obtain
 - In Poisson case, using Newey West standard errors give estimator that is robust to over/under dispersion, zero-inflation, and time series dependence

Time Series Dependence in Nonlinear Models

- Implementation (linear model):
 - In stata, “newey y x1 x2, lag(#)”
 - In r, *sandwich* package:
 - “lm1 <- lm(Y ~ X1 + X2)”
 - “sw1 <- NeweyWest(lm1)”
- Implementation (nonlinear models):
 - In stata, using nwest package
 - In r, *sandwich* package:
 - “glm1 <- glm(Y ~ X1 + X2,family=“poisson”)”
 - “sw1 <- NeweyWest (glm1)”

Time/Group Dependence in Panel Data

- Semiparametric Linear Panel Data Model (short panels with many individuals):

1. $y_{n,t} = \beta' x_{n,t} + \varepsilon_{n,t}$ (linear model)

2. $E[\varepsilon_{n,t} | x_{n,t}] = 0$

3. $E[x_{n,t} x_{n,t}']$ has full rank (identification)

4. $(\varepsilon_{n,1}, \dots, \varepsilon_{n,T})$ are independent over n (independence)

- OLS estimator:

$$\begin{aligned} \hat{\beta} &= \beta_0 + \left[\frac{1}{NT} \sum_{n=1}^N \sum_{t=1}^T x_{n,t} x_{n,t}' \right]^{-1} \left[\frac{1}{NT} \sum_{n=1}^N \sum_{t=1}^T x_{n,t} \varepsilon_{n,t} \right] \\ &= \beta_0 + \left[\frac{1}{N} \sum_{n=1}^N \left(\frac{1}{T} \sum_{t=1}^T x_{n,t} x_{n,t}' \right) \right]^{-1} \left[\frac{1}{N} \sum_{n=1}^N \left(\frac{1}{T} \sum_{t=1}^T x_{n,t} \varepsilon_{n,t} \right) \right] = \beta_0 + \left[\frac{1}{N} \sum_{n=1}^N z_n \right]^{-1} \left[\frac{1}{N} \sum_{n=1}^N \omega_n \right] \end{aligned}$$

$\underbrace{\left(\frac{1}{T} \sum_{t=1}^T x_{n,t} x_{n,t}' \right)}_{=z_n}$
 $\underbrace{\left(\frac{1}{T} \sum_{t=1}^T x_{n,t} \varepsilon_{n,t} \right)}_{=\omega_n}$

Time/Group Dependence in Panel Data

- OLS is unbiased: $E[\hat{\beta} | x] = \beta_0$
- OLS is consistent since, $\frac{1}{N} \sum_{n=1}^N \omega_n \xrightarrow{prob.} 0$
- If $x_{n,t}$ are independent over n and t , then sandwich estimator provides correct standard errors
- Otherwise,

$$Var\left(\frac{1}{\sqrt{NT}} \sum_{n=1}^N \sum_{t=1}^T x_{n,t} \varepsilon_{n,t}\right) = \frac{1}{NT} \sum_{n=1}^N \sum_{t=1}^T Var(x_{n,t} \varepsilon_{n,t}) + \frac{2}{NT} \sum_{n=1}^N \sum_{s < t} Cov(x_{n,t} \varepsilon_{n,t}, x_{n,s} \varepsilon_{n,s})$$

Time/Group Dependence in Panel Data

- Alternatively,

$$\begin{array}{ccc}
 \sqrt{N}(\hat{\beta} - \beta_0) = & \left[\frac{1}{N} \sum_{n=1}^N z_n \right]^{-1} & \left[\frac{1}{\sqrt{N}} \sum_{n=1}^N \omega_n \right] \\
 \downarrow & \downarrow & \downarrow \\
 N(0, E[z_n]^{-1} \text{Var}(\omega_n) E[z_n]) & E[z_n] & N(0, \text{Var}(\omega_n)) \\
 \\
 \text{Var}(\omega_n) \approx \frac{1}{N} \sum_{n=1}^N \omega_n \omega_n' = \frac{1}{N} \sum_{n=1}^N \left[\frac{1}{T} \sum_{t=1}^T x_{n,t} \varepsilon_{n,t} \right] \left[\frac{1}{T} \sum_{t=1}^T x_{n,t} \varepsilon_{n,t} \right]'
 \end{array}$$

- Notice that this will not work with small-long panels since LLN in N will not kick it
- As long as ω_n are independent, variance estimator is accurate (does not require any assumption about time-series dependence)
- Clustering will not control for a common time effect

Time/Group Dependence in Panel Data

- Same principal holds if two-way structure is not individuals/time, but individuals/groups (e.g. countries, states)

$$\hat{\beta} = \beta_0 + \left[\frac{1}{G} \sum_{g=1}^G \left\{ \frac{1}{I_g} \sum_{i=1}^{I_g} x_{g,i} x_{g,i}' \right\} \right]^{-1} \left[\frac{1}{G} \sum_{g=1}^G \left\{ \frac{1}{I_g} \sum_{i=1}^{I_g} x_{g,i} \varepsilon_{g,i} \right\} \right]$$

$$\sqrt{G}(\hat{\beta} - \beta_0) = \left[\frac{1}{G} \sum_{g=1}^G \left\{ \frac{1}{I_g} \sum_{i=1}^{I_g} x_{g,i} x_{g,i}' \right\} \right]^{-1} \left[\frac{1}{\sqrt{G}} \sum_{g=1}^G \left\{ \frac{1}{I_g} \sum_{i=1}^{I_g} x_{g,i} \varepsilon_{g,i} \right\} \right]$$

Time/Group Dependence in Panel Data

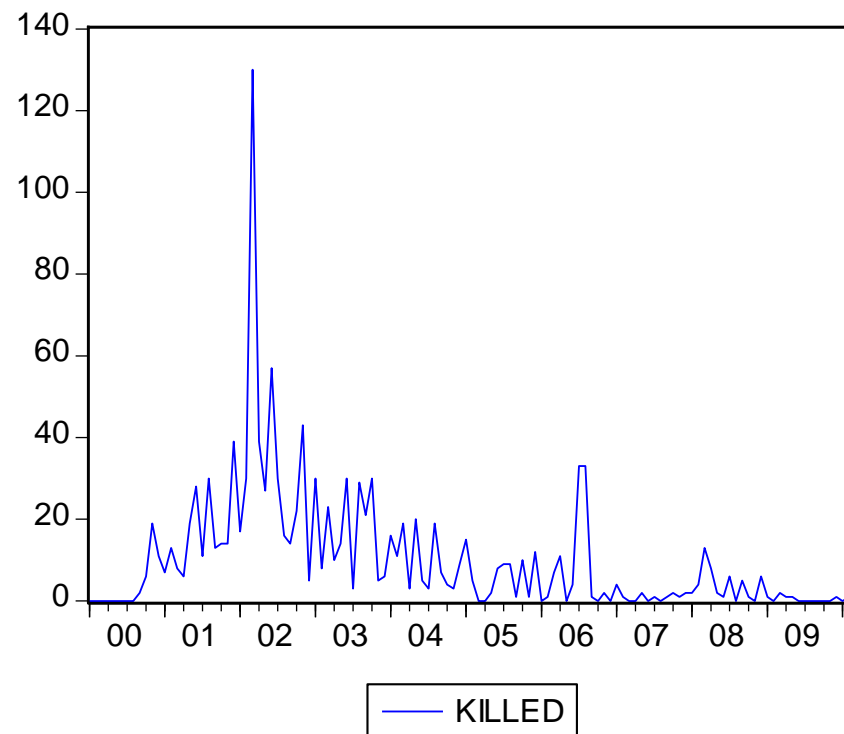
- Suppose there is a group effect, $\varepsilon_{g,i} = u_g + \xi_{g,i}$, u_g and $\xi_{g,i}$ are iid and independent of each other
 - (i.e. individuals in different countries, u_g representing a country effect, possibly due to omitted country variables)
 - If group (e.g. country) fixed effects are excluded, must cluster
 - If group fixed effects are included, no need to cluster
- If country fixed effects are omitted, then clustering deals with within country correlation (as long as $x_{g,i}$ and u_g are not dependent, in which case OLS w/out fixed effects is inconsistent)

Time/Group Dependence in Panel Data

- Implementation:
 - In stata, “regress y x1 x2, cluster(ind)”

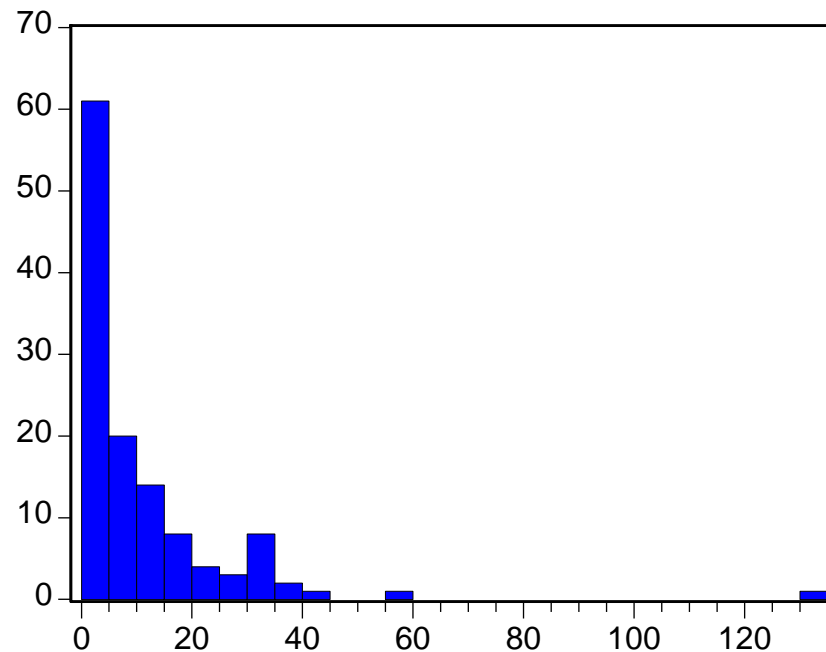
Example: Monthly Terror Attacks in Israel

- Number of Israelis Killed:



Example: Monthly Terror Attacks in Israel

- Number of Israelis Killed:



Series: KILLED	
Sample 2000M01 2010M03	
Observations 123	
Mean	10.00813
Median	5.000000
Maximum	130.0000
Minimum	0.000000
Std. Dev.	15.73265
Skewness	4.160091
Kurtosis	29.29346
Jarque-Bera	3897.928
Probability	0.000000

Example: Monthly Terror Attacks in Israel

- Control for:
 - Election period (3 months leading up to Israeli election)
 - Post peace summit (6 months following peace summit)
 - Right-wing Israeli prime-minister

Example: Monthly Terror Attacks in Israel

- Linear Model in *stata*:
 - Calculate by hand, $m_T = 4$
 - Naïve standard errors, “regress killed killed_m1 elec postsummit rightpm”
 - Robust standard errors, “regress killed killed_m1 elec postsummit rightpm, robust”
 - Newey-West standard errors “newey killed killed_m1 elec postsummit rightpm, lag(4)”

Example: Monthly Terror Attacks in Israel

- Poisson Model in *r*.
 - m_T calculated automatically
 - “mod1 <- glm(killed ~ killed_m1 + elec + postsummit + rightpm,family="poisson",data=xls1)”
 - “coef <- summary(mod1)\$coefficients[1:5,1]”
 - “se1 <- summary(mod1)\$coefficients[1:5,2]”
 - “se2 <- sqrt(diag(sandwich(mod1)))”
 - “se3 <- sqrt(diag(NeweyWest(mod1)))”